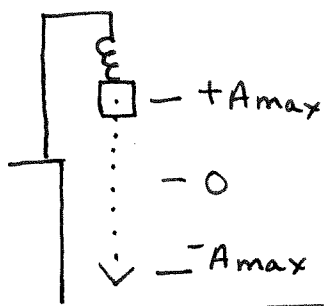


AP Physics Review

SHM

Scenario #1: A mass on a spring



What we know:

E_{Total} is constant as spring-mass oscillate

$E_T = KE + U$ at any given instant. E_T depends on Amplitude

KE_{max} = when mass is @ $y = 0$ (Max Velocity too)

U_{max} = when mass is @ $y = +A$ or $-A$ (Zero Velocity)

$$K_{\text{spring}} = \frac{mg}{x} = \frac{4\pi^2 \text{mass}}{T^2}$$

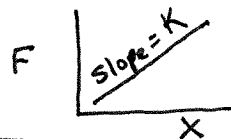
$$T = 2\pi \sqrt{\frac{m}{K}} \quad (T \text{ has units of seconds}) = \frac{2\pi A}{v_{\text{max}}} \text{ or } \text{sec}^{-1}$$

$$\omega = 2\pi f = \sqrt{\frac{K}{m}} \quad (\omega \text{ has units of Radians/sec})$$

$$f = \frac{1}{T} \quad (f \text{ has units of Hz or } \text{sec}^{-1})$$

Cool Stuff:

ω = angular speed = sec^{-1}



Big HINTS:

- Mass affects Period of this Pendulum.

- ω is in radians so set your calculator for

Radians Mode

What we can find out:

1. Find spring constant K

$$K = \frac{mg}{x} = \frac{4\pi^2 m}{T^2} \quad \leftarrow \text{hang a mass and measure period}$$

\leftarrow hang a mass + measure displacement

2. Find position y at any instant (Again, set calculator for RAD Mode!)

$$y = A \cos \omega t = A \cos\left(\frac{2\pi t}{T}\right) = A \cos(2\pi f t) = A \cos \theta \quad \leftarrow \text{starts @ } \pm A = y$$

$$y = A \sin \omega t = A \sin\left(\frac{2\pi t}{T}\right) = A \sin(2\pi f t) = A \sin \theta \quad \leftarrow \text{starts @ } y_0 = 0$$

$\leftarrow t$: time elapsed

$\leftarrow T$: period

RAD MODE

3. Find Velocity at any instant

$$v_{\text{inst}} = \pm \sqrt{\frac{K}{m}(A^2 - x^2)} = \omega A \cos\left(\omega t + \frac{\pi}{2}\right) \quad \leftarrow \text{Starts @ } y_0 = \pm A$$

$$= 2\pi f (\sqrt{A^2 - x^2}) = \frac{2\pi}{T} (\sqrt{A^2 - x^2}) = \omega \sqrt{A^2 - x^2}$$

$$v_{\text{max}} = \pm \sqrt{\frac{K}{m}} (A) = \omega A \quad \leftarrow (\text{recall } \omega = \sqrt{\frac{K}{m}}) = 2\pi f A$$

4. Acceleration @ any instant

$$a = -\omega^2 A \sin \omega t = -\omega^2 x = -\frac{K}{m} A \sin \omega t$$

5. Energy at any instant.

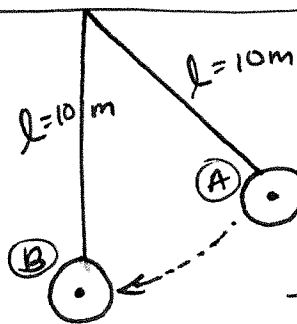
$$E = KE + U = \frac{1}{2} m v^2 + \frac{1}{2} K x^2$$

\leftarrow As x approaches A , velocity drops to zero

AP Physics Review

SHM

Scenario #2 Mass on a string



What we know:

- E_{total} is constant as string swings
- $E = KE + U$
- KE_{max} at bottom of swing
- U_{max} @ Top of either side
- h = vertical distance from position (A) to position (B)

$$T = 2\pi\sqrt{\frac{l}{g}}$$

$$f = \frac{1}{T}$$

What we can find out:

Velocity max : $KE_{max} = U_{max}$
 $\frac{1}{2}mv^2 = mgh$
 $v = \sqrt{2gh}$

$$\cos\theta = \frac{h}{l}$$

$r = l$ (length of rope)

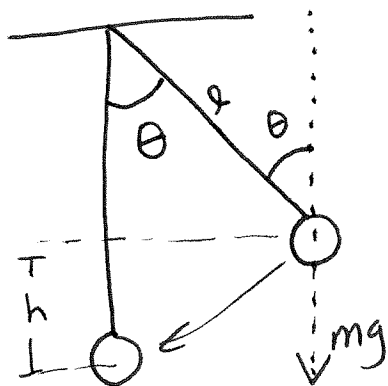
Tension in string:

$$\text{Tension} = mg\cos\theta + F_c = mg\left(\frac{h}{l}\right) + \frac{mv^2}{r}$$

$$\text{Tension} = \frac{mgh}{l} + \frac{m(2gh)}{l} = \frac{3mgh}{l}$$

$$\frac{3mgh}{l}$$

Wow!



Just for Fun: What is Tension @ bottom of swing?

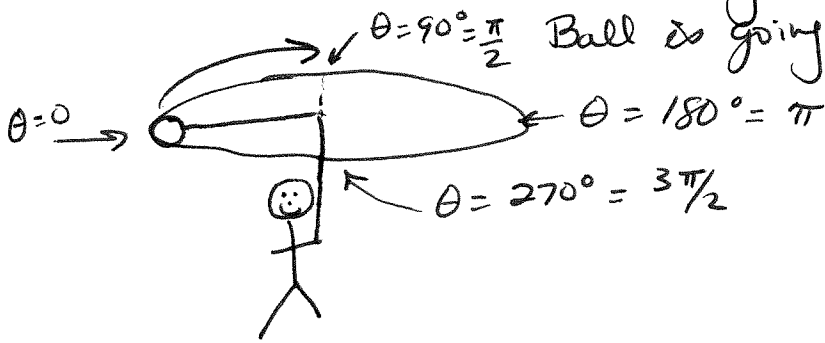
$$\text{Tension} = mg\cos\theta + \frac{mv^2}{l} \quad (\theta = 0^\circ)$$

$$\text{Tension} = mg + \frac{mv_{max}^2}{l}$$

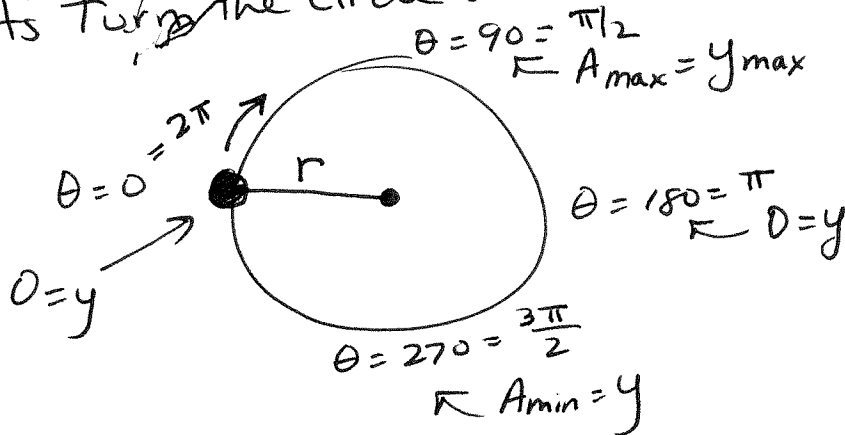
AP Physics Review

Scenario # 3:

Computing SHM of a ball on a string
Ball is going around + around



Let's Turn the circle on its side for easier viewing:



$\text{radius} = A_{\text{max}}$

$$y = A \sin \omega t$$

$$= r \sin \omega t$$

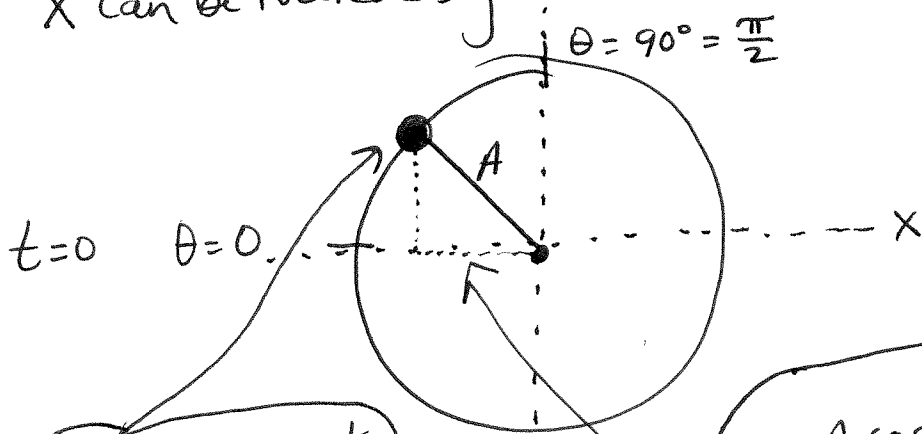
$$= r \sin \theta t$$

Sin because we start @ $y=0$

if θ is in radians

- $\omega = \text{Time it takes to go around circle once (Sec}^{-1}\text{)}$
 $= 2\pi f = 2\pi \left(\frac{\text{\# of revolutions}}{1 \text{ sec}} \right)$
- Circumference = $2\pi r$

X can be found by : $X = A \cos \omega t = r \cos \omega t$



Position of ball is x, y

$y = A \sin \omega t$

note: @ $t=0$, y is min

$X = A \cos \omega t$

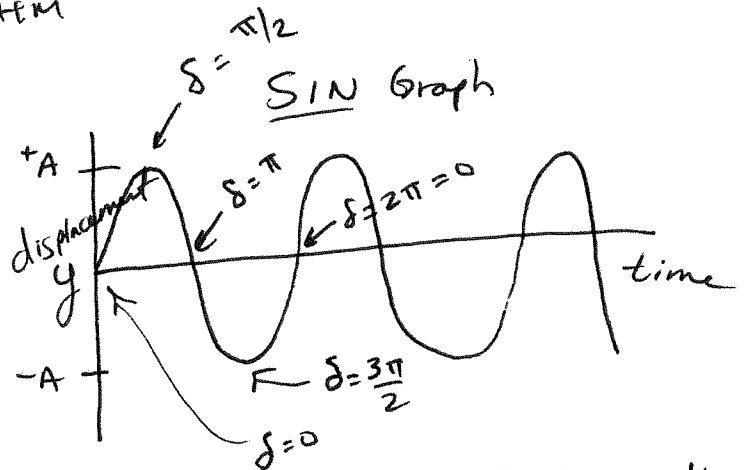
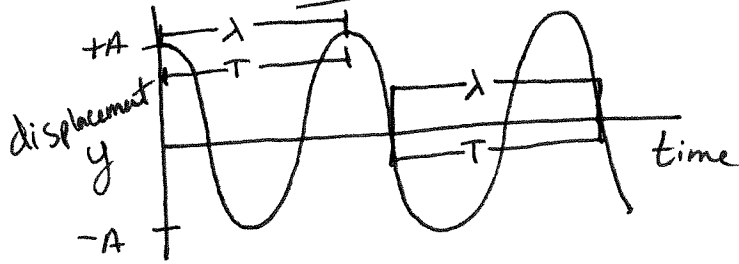
note, @ $t=0$, x is max

AP Physics Review

STEM

Reading Sin + Cos graphs

Cos Graph



λ = wavelength = distance between 2 crests or 2 troughs or 2 nodes in same direction.

T = Period = Time it takes for 1λ to pass by

f = frequency = number of λ 's per second

v = wave velocity = $\lambda f = (\text{meters}) \left(\frac{1}{\text{sec}}\right)$

Cos Graph

$$y = A \cos \omega t = A \sin \omega t + \frac{\pi}{2}$$

RAD MODE

$v_{\text{inst}} = \omega A \cos \left(\omega t + \frac{\pi}{2}\right)$ ← Why $\pi/2$?
because velocity is 90° out of phase w/ displacement

v_{inst} = Tangent to the line @ any point

T = Time between wavelengths

$$f = 1/T$$

SIN Graph

$$y = A \sin \omega t = A \cos \omega t + \frac{\pi}{2}$$

RAD MODE

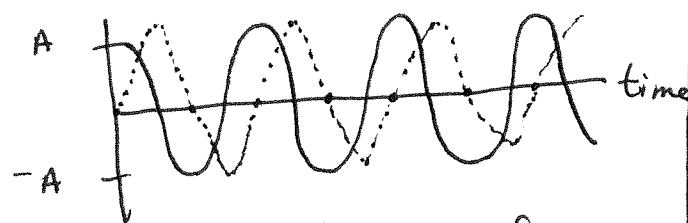
$$v_{\text{inst}} = \omega A \cos \left(\omega t + \frac{\pi}{2}\right)$$

v_{inst} = Tangent to line @ any point.

Remember, you can replace ω with $2\pi f$ or $\frac{2\pi}{T}$

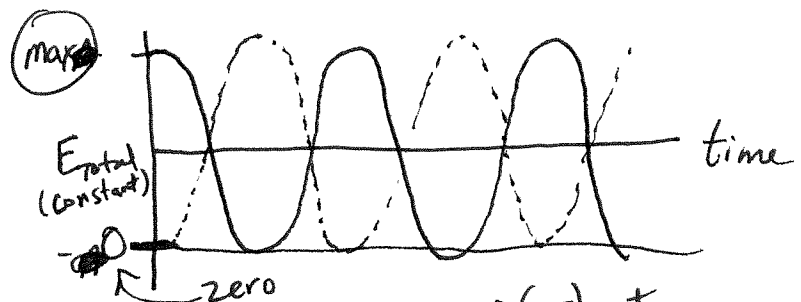
Compare graphs

Displacement — vs. Velocity —



Velocity is $90^\circ \left(\frac{\pi}{2}\right)$ out of phase w/ displacement. Think Mass on a spring

KE — v. Potential E



KE and Potential are $180^\circ \left(\pi\right)$ out of phase w/ Each other. E_{total} is the sum of $KE + U$ @ any instant